## WACHENDORFF

## Wachendorff Automation GmbH \& Co. KG

Industriestraße 7 • D-65366 Geisenheim
Tel.: +49 (0) 6722/99 65-25 • Fax: +49 (0) 6722/9965-70
E-Mail: wdg@wachendorff.de • www.wachendorff-automation.com

## System - Circumferential belt measuring system Silent Move WDGMSUN For heights up to 70 metres ( 230 ft )



The quiet Silent Move belt shaft copying devices are systems which are installed quickly and easily in the shaft.
All installation components required for standard installation to the lift cab rail or on the wall are supplied.

- Measuring set for easy installing the belt on existing brackets in the elevator shaft.
- Quiet and non-slip digital shaft copying for universal mounting on a lift cabin
- Use up to speeds of $4 \mathrm{~m} / \mathrm{s}(800 \mathrm{ft} / \mathrm{min})$.
- Particularly quiet and smooth-running, thanks to special belts and low-noise suspension.
- User-friendly, reliable alternative to switches and sensors.
- Accuracy in the shaft:
- Incremental encoder WDGI58B
up to $0.08 \mathrm{~mm} /$ pulse ( 0.0031496 inch/pulse) at 5000 pulses
- Absolute encoder WDGA58B multiturn, with

CANopen interface: 4,096 steps/turn and 262,144 (18 bit multiturn) turns, CANopen LIFT interface: 4,096 steps/turn and 262,144 (18 bit multiturn) turns or SSI interface: 4,096 (12 bit) steps/turn and 8,192 (13 bit multiturn) turns

- Quick and easy mounting with our complete belt fixing and tensioning set.
www.wachendorff-automation.com/silent-move

Noticeably quieter in a noise comparison*:
Conventional System: 92 db
Silent Move: 68 db
*measured directly at the idler pulley at $4 \mathrm{~m} / \mathrm{sec}(800 \mathrm{ft} / \mathrm{min})$.

Put together your own system for shaft copying, by selecting an encoder and specifying the length of the special belt.


Incremental encoder
WDGI58B

Incremental encoders WDGI:
Calculation of resolution in the shaft:
Effective circumfrerence of pulley: 401.11 mm ( 15.7917322835 inch)

$$
\text { Res. in } \mathrm{mm} \text { (inch) }=\frac{401.11 \mathrm{~mm}(15.7917322835 \text { inch) }}{\text { Pulse number of encoder (PPR) }}
$$

Res. in pulses $/ \mathrm{mm}$ (inch) $=\frac{\text { Pulse number of encoder (PPR) }}{401.11 \mathrm{~mm}(15.7917322835 \text { inch })}$

## Calculation of the limit frequency:

$\mathrm{fg}(\mathrm{Hz})=\frac{\text { Pulse number of encoder }(\mathrm{PPR}) \times \text { max. speed }(\mathrm{m} / \mathrm{sec})(\mathrm{ft} / \mathrm{sec})}{0.40111 \mathrm{~m}(1.3153999 \mathrm{ft})}$

## Calculation of the traverse path:

$\mathrm{s}(\mathrm{m})(\mathrm{ft})=\frac{\text { Pulses (l) }}{\text { Pulse number of encoder (PPR) }} \times 0.40111 \mathrm{~m}(1.3153999 \mathrm{ft})$


Absolute encoder
WDGA58B

Absolute encoders WDGA:
Repeat precision with WDGA: +/- 0.223 mm ( 0.00877951 inch)


Self-guiding special belt for exceptionally quiet, non-slip measuring with noise-reducing wheel.

Ordering information - Circumferential belt measuring system WDGMSUN:

| Description: | Order No.: |
| :--- | :--- |
| Incremental variants |  |
| System (without encoder): |  |
| 2 guide pulleys, encoder attachment, tensioning device for the belt and corresponding | WDGMSUN |
| assembly components. Please order the special belt separately. |  |
| (see below: Silent Move special belt, calculation of length) |  |
| System with incremental encoder WDGI 58B10600ABNH24SC8 and 15 m cable (KI 8-67-15S): | WDGMSUN58B10600ABNH24SC8 |
| For an accuracy of measurement of 0.669 mm ( 0.03 inch ) or $1.5 \mathrm{pulses} / \mathrm{mm}(37.99$ pulses/inch) with a |  |
| limit frequency of 5.98 kHz and a cab speed of $4 \mathrm{~m} / \mathrm{s}(787.4 \mathrm{ft} / \mathrm{min})$. |  |
| Encoder type 58B10600ABNH24SC8: Shaft: $\varnothing 10$ mm, pulse number: 600 PPR, channels AB and |  |
| zero pulse, power supply 10 VDC up to 30 VDC , channels push-pull, sensor connector 8-pol. radial, |  |
| 15 m cable (KI 8-67-15 S) |  |

System with incremental encoder 58B101000ABNH24SC8 and 15 m cable (KI 8-67-15 S):
For an accuracy of measurement of 0.4 mm ( 0.02 inch) or 2.5 pulses $/ \mathrm{mm}$ ( 63.324 pulses/inch) with a limit frequency of 9.972 kHz and a cab speed of $4 \mathrm{~m} / \mathrm{s}(787.4 \mathrm{ft} / \mathrm{min})$.
Encoder type 58B101000ABNH24SC8: Shaft: $\varnothing 10 \mathrm{~mm}$, pulse number: 1,000 PPR, channels $A B$ and zero pulse, power supply 10 VDC up to 30 VDC, channels push-pull, sensor connector 8-pol. radial, 15 m cable (KI 8-67-15 S)

System with incremental encoder 58B102500ABNH24SC8 and 15 m cable (KI 8-67-15 S):
For an accuracy of measurement of 0.16 mm ( 0.01 inch ) or 6.23 pulses $/ \mathrm{mm}$ ( 158.31 pulses/inch) with a limit frequency of 24.93 kHz and a cab speed of $4 \mathrm{~m} / \mathrm{s}(787.4 \mathrm{ft} / \mathrm{min})$.
Encoder type 58B102500ABNH24SC8: Pulse number: 2,500 PPR, channels AB and zero pulse, power supply 10 VDC up to 30 VDC, channels push-pull, sensor connector 8-pol. radial,
15 m cable (KI 8-67-15 S)

## Find your incrementalen encoder:

With the aid of the calculation forms for limit frequency and resolution in the shaft and the data sheet WDGI58B. All variants defined except optional shaft sealed to IP67.

Absolute variants WDGA58B CANopen, CANopen LIFT or WDGA58B SSI

## System with absolute multiturn encoder with CANopen CiA 406 interface:

For an accuracy of measurement of 0.0979 mm ( 0.0038 inch) or 10.21 steps $/ \mathrm{mm}$ ( 259.38 steps/inch). Binary Code: 4,096 (12 bit) steps/revolution and max. 262,144 (18 bit) revolutions.
Power supply 10 VDC up to 30 VDC, 5 pin. connector, radial, 10 m bus line connector and female connector, T -junction, termination resistor.

System with absolute multiturn encoder with CANopen LIFT CiA 417 interface:
For an accuracy of measurement of 0.0979 mm ( 0.0038 inch) or 10.37 steps $/ \mathrm{mm}(259.38$ steps/inch), configurable. Binary Code: 4,096 (12 bit) steps/revolution and max. 262,144 (18 bit) revolutions, configurable. Power supply 10 VDC up to 30 VDC, 5 pin. connector, radial 10 m bus line connector and female connector, T -junction, termination resistor.

System with absolute multiturn encoder with synchronous serial interface SSI*:
For an accuracy of measurement of 0.0979 mm ( 0.0038 inch) or 10.21 steps $/ \mathrm{mm}$ ( 259.38 steps/inch).

* Gray Code (G)/Binary Code (B): 4,096 (12 bit) steps/revolution and 8,192 (13 bit) revolutions.

Power supply 10 VDC up to 30 VDC, 8 pin connector, radial, 10 m cable
Comprehensive technical information on WDGA 58B CANopen / WDGA 58B CANopen LIFT /
WDGA 58B SSI - www.wachendorff-automation.com/wdga58bcan /wdga58bcanlift /wdga58bssi

## Silent Move special belt:

Calculation of the length: Transport height $\times 2+10 \mathrm{~m}$ (extend accordingly for transition points)
20 m
35 m
50 m
60 m
80 m
200 m-drum
500 m-drum
Special nubbed belt ( $X X X=$ figures in metres)

## WDGMSUN58B101000ABNH24SC8

WDGMSUN58B102500ABNH24SC8

WDGMSUN58B10XXXXYYYZZZSC8

WDGMSUN58B101218COAB00CC5

WDGMSUN58B101218CLAB00CC5

WDGMSUN58B101218SIAX01CC8
$X=G$ or $B$

WDGNR020
WDGNR035
WDGNR050
WDGNR060
WDGNR080
WDGNR200
WDGNR500
WDGNRXXX

